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Claim 157. (Amended) A system for automatically videoing the activities movements of one or more participants or objects; as they move about within a predefined the entire performance area; of a sporting, theatre or concert event, during a predefined throughout the entire time duration of the event, comprising:

a first set of two or more multiple stationary overhead cameras, not capable of pan, tilt or zoom movement, sufficient to form a contiguous field-of-view of said entire performance area, for generating a first video stream of images that together form a contiguous view of the predefined area continuously throughout the predefined said entire time duration;

a first algorithm operated on a computer system exclusively and solely responsive to the said first stream of video images for continuously and simultaneously analyzing the images from each first cameras all cameras in said first set of multiple stationary cameras in order to detect the presence of any one or more participants or objects each participant or object within each and every camera's view, to determine for each detected participant or object its relative centroid two-dimensional location centroid coordinates within that view, and to combine use this determined information from each and every all said first set cameras cameras into for updating a real-time tracking database of at least the ongoing centroid two-dimensional coordinates centroid location of each one or more participants or objects participant or object, relative to the said entire predefined performance area, where said real-time tracking database includes all current and past said centroid locations determined throughout said entire time of said event, and

a second algorithm operated on a computer system exclusively and solely responsive to the said real-time tracking database for dynamically automatically and individually adjusting the current view of each one or more cameras camera in a second set of movable multiple stationary cameras, capable of pan, tilt and zoom movement distinct from the said first set of stationary cameras, wherein each movable said second set camera is automatically directed without operator intervention to maintain an independent view of one or more the participants or objects, where the said second set

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of ~~movable~~ cameras outputs a second stream of video images for viewing and recording, and where the wherein said second stream of video images is not used to either determine any participant's or object's ~~centroid~~ two-dimensional ~~coordinates centroid locations~~ or to otherwise update the said real-time tracking database.

Claim 158. (Amended) The system of claim 157 wherein the contiguous view field-of-view formed by the said first set of stationary overhead cameras is substantially parallel to the ground surface within the predefined said entire performance area.

Claim 159. (Amended) The system of claim 157 for further providing a three dimensional model of the activities movements of one or more participants or objects, further comprising:

a third algorithm operated on a computer system responsive to the said real-time tracking database and the said first or and said second streams of video images for determining the ongoing relative three-dimensional coordinates of one or more specific, non-centroid locations on each participant or object and for updating the said real-time tracking database to include the additional three-dimensional coordinates of all detected locations matched with the respective participants or objects.

Claim 160. (Amended) The system of claim 159 further comprising:

markers adhered onto one or more locations on each participant or object to be tracked, where the said markers are detectable by the said first or said second set of stationary cameras, and where the said first or said third algorithms now determine the locations of the adhered said markers and update the said real-time tracking database with the related ongoing three-dimensional coordinates of each detected marker for forming the three dimensional model of each participant's activities movements.

Claim 161. (Amended) The system of claim 160 wherein the said markers are substantially transparent to the participants, further comprising:

said markers adhered onto participants that reflect, retroreflect or fluoresce primarily non-visible energy and are therefore substantially visibly transparent, and

one or more energy sources emitting non-visible energy that is reflected or retroreflected off of the said markers, or emitting energy that is fluoresced in the non-

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visible spectrum by the said markers and is detectable by the said first or said second set of stationary cameras.

Claim 162. (Amended) The system of claim 161 wherein the participants are additionally identified, further comprising:

at least one uniquely encoded marker adhered onto an upper surface of each participant to be identified, and

a forth algorithm operated on a computer system for locating and recognizing the said encoded markers within the said first stream of video images and for updating the said real-time tracking database with each participant's identity matched to their coordinates.

Claim 163. (Amended) The system of claim 162 wherein the said uniquely encoded markers are substantially transparent to the participants, further comprising:

said uniquely encoded markers that reflect, retroreflect or fluoresce primarily non-visible energy and are therefore substantially visibly transparent, and

one or more energy sources emitting non-visible energy that is reflected or retroreflected off of the said encoded markers, or emitting energy that is fluoresced in the non-visible spectrum by the said encoded markers and is detectable by the said first set of stationary overhead cameras.

Claim 164. (Amended) The system of claim 157 wherein the participants are additionally identified, further comprising:

at least one uniquely encoded marker adhered onto an upper surface of each participant to be identified, and

a third algorithm operated on a computer system for locating and recognizing the said encoded markers within the said first stream of video images and for updating the said real-time tracking database with each participant's identity matched to its their coordinates.

Claim 165. (Amended) The system of claim 164 wherein the said uniquely encoded markers are substantially transparent to the participants, further comprising:

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said uniquely encoded markers that reflect, retroreflect or fluoresce primarily non-visible energy and are therefore substantially visibly transparent, and

one or more energy sources emitting non-visible energy that is reflected or retroreflected off of the said markers, or emitting energy that is fluoresced in the non-visible spectrum by the said markers and is detectable by the said first set of stationary overhead cameras.

Claim 166. (Amended) The system of claim 157 for videoing the activities movements of two or more participants, wherein the said second set of moveable stationary cameras, capable of pan, tilt and zoom movement, comprises at least two cameras and wherein the said second set is additionally directed to automatically reassign any one or more of said second set cameras currently following any one or more participants to instead follow a different one or more participants based upon which camera views are currently blocked by one or more participants in front of another, or upon which camera views are best situated to capture the programmatically desired view of any given participant or game object.

Claim 167. (Amended) A method for automatically videoing the activities movements of one or more participants or objects as they move about within a predefined the entire performance area of a sporting, theatre or concert event, during a predefined throughout the entire time duration of the event, comprising the steps of:

capturing a first stream of video images using a first set of two or more multiple stationary overhead cameras, not capable of pan, tilt or zoom movement, wherein the combined view from all first cameras covers the sufficient to form a contiguous field-of-view of said entire predefined performance area, and where each said first set camera provides images continuously throughout the predefined said entire time duration;

simultaneously analyzing only the said first stream of video images coming from each said first camera set of multiple stationary overhead cameras in order to continuously detect the presence of any one or more participants or objects within each and every camera's view, to determine each detected participant's or object's relative centroid two-dimensional location centroid coordinates within that view, and to combine use this determined information from each and every all said first set camera cameras into

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for updating a real-time tracking database of at least the ongoing centroid the two-dimensional coordinates centroid location of each one or more participants or objects participant or object, relative to the said entire predefined performance area, where said real-time tracking database includes all current and past said centroid locations determined throughout said entire time of said event;

using the said determined participant and object locations stored in said real-time tracking database to automatically and individually direct adjust, without the aid of an operator, ~~some combination of at least the pan, tilt or zoom movements of each camera in a the current view of each camera in a second set of one or more movable multiple stationary cameras, capable of pan, tilt and zoom movement~~, distinct from the said first set of stationary overhead cameras, and

capturing a second stream of video images for viewing and recording using the from said second set of automatically movable multiple stationary cameras, wherein the said second stream of video images create independent views of one or more of the participants or objects within the predefined said entire performance area and where the wherein said second stream of video images is not used to either determine any participant's or object's centroid two-dimensional coordinates centroid locations or to otherwise update the said real-time tracking database.

Claim 168. (Amended) The method of claim 167 wherein the contiguous field-of-view formed by the said first set of stationary overhead cameras is arranged so that its combined, contiguous view of the predefined area is substantially parallel to the ground surface within the said entire predefined performance area.

Claim 169. (Amended) The method of claim 167 for further providing a three dimensional model of the activities movements of one or more the participants or objects, comprising the additional step of:

analyzing the said real-time tracking database and ~~both the said first and said second streams of video images to determine the ongoing relative three-dimensional coordinates of one or more specific, non-centroid locations on each participant or object and for updating the said real-time tracking database to include the additional~~

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three-dimensional coordinates of all detected locations matched with the respective participants or objects.

Claim 170. (Amended) The method of claim 169 further comprising the steps of:

adhering markers onto the one or more locations on each participant or object to be tracked;

detecting ~~the said~~ markers using computer based image analysis of ~~the said~~ first or ~~said~~ second streams of video in order to determine the ongoing relative three-dimensional coordinates of each marker, and

updating ~~the said real-time~~ tracking database to indicate the ongoing relative three-dimensional coordinates of ~~the said~~ detected markers matched with the respective participants or objects.

Claim 171. (Amended) The method of claim 170 wherein ~~the said~~ markers are substantially transparent to the participants, further comprising the steps of:

using ~~said~~ markers that reflect, retroreflect or fluoresce primarily non-visible energy and are therefore substantially visibly transparent, and

using one or more energy sources to emit non-visible energy throughout ~~the said predefined entire performance~~ area, to be reflected or retroreflected off of ~~the said~~ markers, or emitting energy that is fluoresced in the non-visible spectrum by ~~the said~~ markers, where the non-visible energy is detectable by ~~the said~~ first or ~~said~~ second set of stationary cameras.

Claim 172. (Amended) The method of claim 171 ~~for additionally identifying wherein the participants are additionally identified~~, further comprising the steps of:

placing at least one uniquely encoded marker onto ~~a-top~~ an upper surface of each participant to be identified;

detecting and recognizing each encoded marker using computer based image analysis of ~~the said~~ first stream of video images, and

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updating the said real-time tracking database to indicate the identity of each participant matched to their coordinates.

Claim 173. (Amended) The method of claim 172 wherein the uniquely encoded markers are substantially transparent to the participants, further comprising the steps of:

using said uniquely encoded markers that reflect, retroreflect or fluoresce primarily non-visible energy and are therefore substantially visibly transparent, and

using one or more energy sources to emit non-visible energy throughout the predefined said entire performance area, to be reflected or retroreflected off of the said encoded markers, or emitting energy that is fluoresced in the non-visible spectrum by the said encoded markers, where the non-visible energy is detectable by the said first set of stationary overhead cameras.

Claim 174. (Amended) The method of claim 167 for additionally identifying wherein the participants are additionally identified, further comprising the steps of:

placing at least one uniquely encoded marker onto a top an upper surface of each participant to be identified;

detecting and recognizing each said encoded marker using computer based image analysis of the said first stream of video images, and

updating the said real-time tracking database to indicate the identity of each participant matched to their coordinates.

Claim 175. (Amended) The method of claim 174 wherein the said uniquely encoded markers are substantially transparent to the participants, further comprising the steps of:

using uniquely encoded markers that reflect, retroreflect or fluoresce primarily non-visible energy and are therefore substantially visibly transparent, and

using one or more energy sources to emit non-visible energy throughout the predefined said entire performance area, to be reflected or retroreflected off of the said encoded markers, or emitting energy that is fluoresced in the non-visible spectrum by the said encoded markers, where the non-visible energy is detectable by the said first set of stationary overhead cameras.

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Claim 176. (Amended) The method of claim 167 for videoing the ~~activities~~ movements of two or more participants from optimal viewpoints, further comprising the steps of:

using two or more cameras in the said second set of movable stationary cameras, and during the step of individually ~~directing at least~~ adjusting the pan, tilt or zoom movements of each camera in the said second set of stationary cameras, capable of pan, tilt and zoom movement, dynamically considering the location of each participant or object with respect to the view of each said second set camera and automatically reassigning any one or more said second set cameras currently following any one or more participants or objects to instead follow a different one or more participants or objects based upon which camera views are best situated to capture the programmatically desired view of any given participant or game object.